



SFM60-H1BB4K02

SFS/SFM60

MOTOR FEEDBACK SYSTEMS ROTARY HIPERFACE®



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Ordering information

| Туре | Part no. |
|----------------|------------|
| SFM60-H1BB4K02 | On request |

Other models and accessories → www.sick.com/SFS_SFM60

Illustration may differ



Detailed technical data

Performance

| Number of sine/cosine periods per revolution | 1,024 |
|--|--|
| Number of the absolute ascertainable revolutions | 4,096 |
| Total number of steps | 134,217,728 |
| Measuring step | 0.3 Winkelsekunden For interpolation of the sine/cosine signals with, e. g., 12 bits |
| Integral non-linearity | \pm 45 Winkelsekunden, Error limits for evaluating sine/cosine period, without mechanical tension of the stator coupling |
| Differential non-linearity | ± 7 Winkelsekunden, Non-linearity within a sine/cosine period |
| Operating speed | 6,000 min ⁻¹ , up to which the absolute position can be reliably produced |

Interfaces

| Type of code for the absolute value | Binary |
|-------------------------------------|--|
| Code sequence | Rising, For clockwise shaft rotation, looking in direction "A" (see dimensional drawing) |
| Communication interface | HIPERFACE® |
| Available memory area | 1,792 Byte |

Electrical data

| Supply voltage range | 7 V DC 12 V DC |
|--|-----------------------|
| Recommended supply voltage | 8 V DC |
| Operating power consumption (no load) | < 80 mA ¹⁾ |
| Output frequency for sine/cosine signals | 0 kHz 200 kHz |

¹⁾ Without load.

Mechanical data

| Shaft version | Blind hollow shaft |
|------------------|--------------------|
| Shaft material | Stainless steel |
| Flange material | Zinc diecast |
| Housing material | Aluminum die cast |

 $^{^{1)}}$ Take into account self-heating of 3.3 K per 1,000 rpm when designing the operating temperature range.

| Flange type / stator coupling | Stator coupling |
|---|---|
| Dimensions | See dimensional drawing |
| Weight | ≤ 0.25 kg |
| Moment of inertia of the rotor | 40 gcm ² |
| Operating speed | ≤ 9,000 min ^{-1 1)} |
| Angular acceleration | ≤ 500,000 rad/s² |
| Operating torque | 0.6 Ncm (+20 °C) |
| Start up torque | 0.8 Ncm (+20 °C) |
| Permissible shaft movement, radial static/dynamic | $\pm 0.3 \text{mm} / \pm 0.1 \text{mm}$ |
| Permissible shaft movement, axial static/dynamic | ± 0.5 mm / ± 0.2 mm |
| Life of ball bearings | 3.6 x 10^9 revolutions |
| Connection type | Male connector M12, 8-pin, radial |

 $^{^{1)}}$ Take into account self-heating of 3.3 K per 1,000 rpm when designing the operating temperature range.

Ambient data

| Operating temperature range | -40 °C +115 °C |
|---|---|
| Storage temperature range | -40 °C +115 °C, without package |
| Relative humidity/condensation | 90 %, Condensation not permitted |
| Resistance to shocks | 100 g, 6 ms (according to EN 60068-2-27) |
| Frequency range of resistance to vibrations | 20 g, 10 Hz 2,000 Hz (according to EN 60068-2-6) |
| EMC | According to EN 61000-6-2 and EN 61000-6-3 1) |
| Enclosure rating | IP65, with mating connector inserted (according to IEC 60529) |

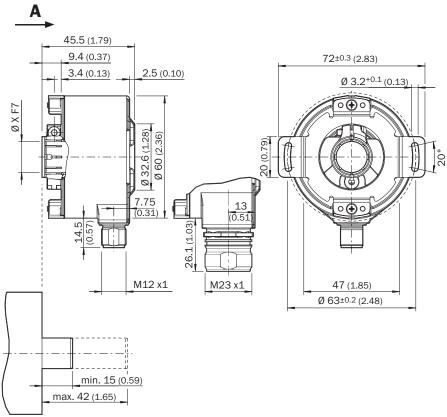
¹⁾ The EMC according to the standards quoted is achieved when the motor feedback system is mounted in an electrically conductive housing, which is connected to the central earthing point of the motor controller via a cable screen. The GND-(0 V) connection of the supply voltage is also grounded here. If other shielding concepts are used, users must perform their own tests.

Classifications

| ECI@ss 5.0 | 27270590 |
|----------------|----------|
| ECI@ss 5.1.4 | 27270590 |
| ECI@ss 6.0 | 27270590 |
| ECI@ss 6.2 | 27270590 |
| ECI@ss 7.0 | 27270590 |
| ECI@ss 8.0 | 27270590 |
| ECI@ss 8.1 | 27270590 |
| ECI@ss 9.0 | 27270590 |
| ETIM 5.0 | EC001486 |
| ETIM 6.0 | EC001486 |
| UNSPSC 16.0901 | 41112113 |

Dimensional drawing (Dimensions in mm (inch))

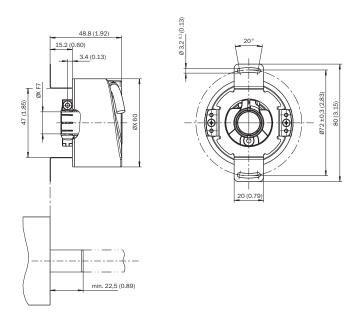
Blind hollow shaft, male connector connection - standard system



General tolerances according to DIN ISO 2768-mk

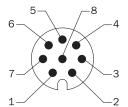
Proposed fitting

Version 4



PIN assignment

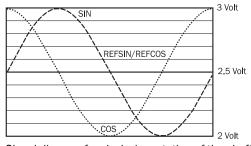
View of the M12 male connector plug-in face



| PIN | Signal | Explanation | |
|---------|----------------|---------------------------------------|--|
| 1 | REFSIN | Process data channel | |
| 2 | + SIN | Process data channel | |
| 3 | REFCOS | Process data channel | |
| 4 | + COS | Process data channel | |
| 5 | Data + | Parameter channel RS 485 | |
| 6 | Data - | Parameter channel RS 485 | |
| 8 | U _S | Supply voltage | |
| Housing | Screen | Screen connected with encoder housing | |

Diagram

Signal specification of the process channel



Signal diagram for clockwise rotation of the shaft looking in direction "A" (see dimensional drawing)1 period = $360 \degree : 1024$

Recommended accessories

Other models and accessories → www.sick.com/SFS_SFM60

| | Brief description | Туре | Part no. |
|---------|---|-------------|----------|
| Flanges | | | |
| | Stator coupling, 16.5 mm high | BEF-DS05XFX | 2057423 |
| | Stator coupling with hole circle diameter 63 mm | BEF-DS07XFX | 2059368 |

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| | Brief description | Туре | Part no. |
|-------------|--|---------------|----------|
| Programming | and configuration tools | | |
| le sell' | SVip® LAN programming tool for all motor feedback systems | PGT-11-S LAN | 1057324 |
| | SVip® WLAN programming tool for all motor feedback systems | PGT-11-S WLAN | 1067474 |

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